

Lecture 14 - March 3

Model Checking

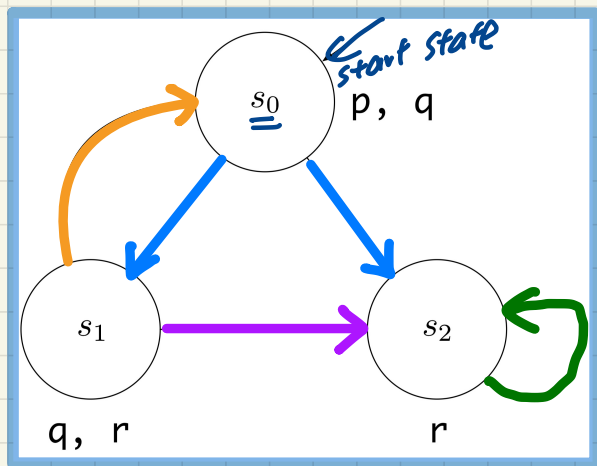
Unfolding/Unwinding Paths

Satisfaction Relations: Path vs. Model

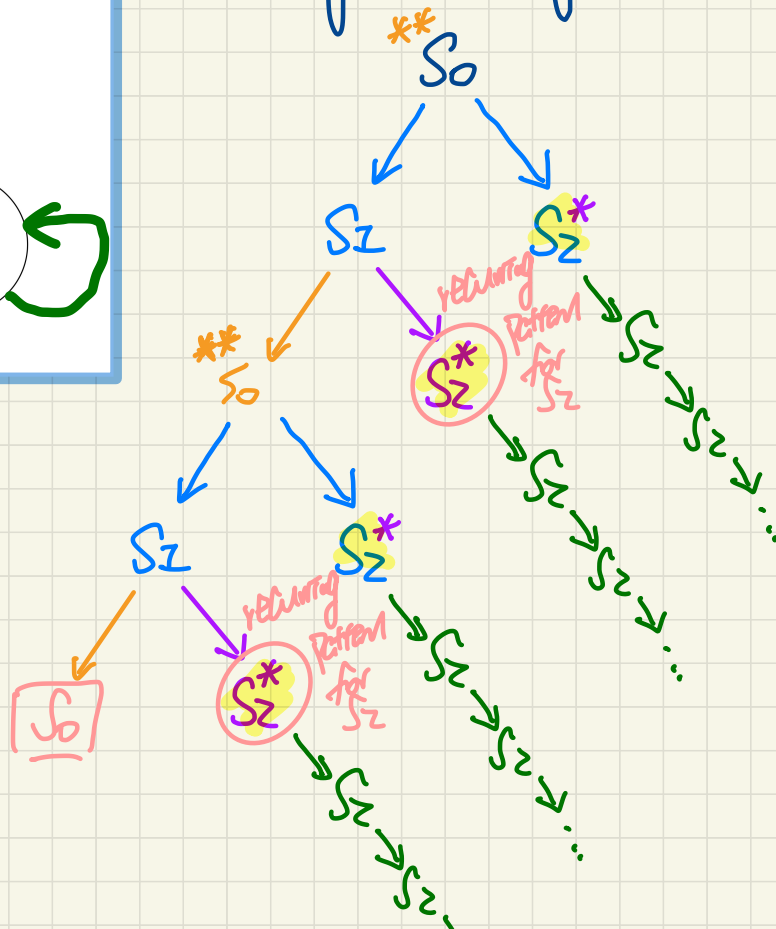
Formulations: X , F , G

Announcements/Reminders

- ProgTest1 results to be released (by end of Friday)
- **WrittenTest1** guide & examples released
 - + **Review Q&A** (Zoom): 7:30pm on Monday, Mar 3
- **Lab3** to be released after WrittenTest1
- Office Hours: 3pm to 4pm, Mon/Tue/Wed/Thu
- TA contact information (on-demand for labs) on eClass

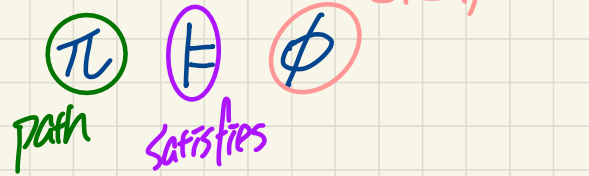


Unfolding/Unwinding (transitions)



Satisfaction Relations

(1) Path Satisfaction



(2) Model Satisfaction



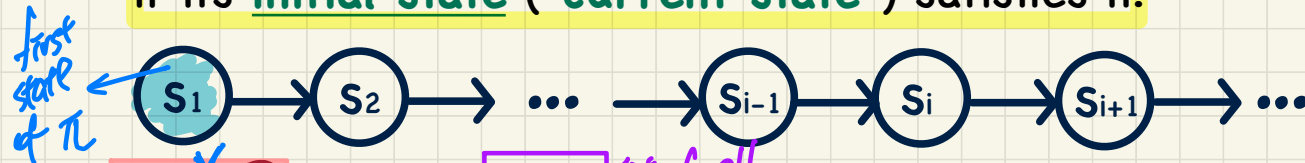
model
formulated
as an LTS

$S \in S$

need to consider all paths
starting from state S .

Path Satisfaction: Logical Operations

A **path** satisfies a **proposition** if its **initial state** ("current state") satisfies it.



base cases

$$\pi \models p \Leftrightarrow p \in \mathcal{L}(S_1) \quad \text{set of all propositional atoms satisfied in the 1st state } (S_1) \text{ of } \pi, p \in \mathcal{L}(S_1)$$

$$\pi \models \top \quad (\text{whether the 1st state of } \pi \text{ satisfies } \top)$$

$$\pi \models \perp$$

* $\forall i. i \% 2 = 0 \wedge i > 0 \Rightarrow \pi^i \models p$
 2, 4, 6, ...

path starting from the i -th component of π

$$\forall i. i \in \mathbb{N} \wedge i > 0 \Rightarrow \pi^{2i} \models p$$

relevant cases.

$$\pi \models \neg \phi \Leftrightarrow \neg(\pi \models \phi)$$

$$\pi \models \phi_1 \wedge \phi_2 \Leftrightarrow \pi \models \phi_1 \wedge \pi \models \phi_2$$

$$\pi \models \phi_1 \vee \phi_2 \Leftrightarrow \pi \models \phi_1 \vee \pi \models \phi_2$$

$$\pi \models \phi_1 \Rightarrow \phi_2 \Leftrightarrow \pi \models \phi_1 \Rightarrow \pi \models \phi_2$$

* Q: Express that all the

even-numbered states satisfies a proposition p .

S_2, S_4, S_6, \dots

Path Satisfaction: Temporal Operations (1)

A **path** satisfies $X\phi$ *next op.* *voted, arbitrarily complicated CTL formula.*
if the **next state** (of the "current state") satisfies it.

$$\pi \models X\phi$$

$$\pi^2 \models \phi$$

$$\pi = S_1 \rightarrow S_2 \rightarrow S_3 \rightarrow S_4 \rightarrow S_5 \rightarrow \dots$$



Formulation (over a path)

Q. What is $\pi^3 \models Xp$ checking?

$$\pi \models X\phi \Leftrightarrow \boxed{\pi^2} \models \phi$$

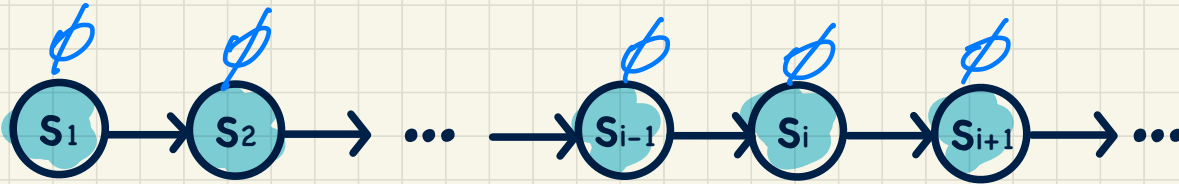
a path starting from the 2nd component of ϕ

$$\pi^3 \models Xp \Leftrightarrow (\pi^3)^2 \models p$$

$$\boxed{\pi^4} \models p \Leftrightarrow p \in \angle(S_4)$$

Path Satisfaction: Temporal Operations (2)

A **path** satisfies $\overset{\text{Global}}{G}\phi \rightarrow$ *Hereforth, ϕ is true.*
 if the every state satisfies it.



Formulation (over a path)

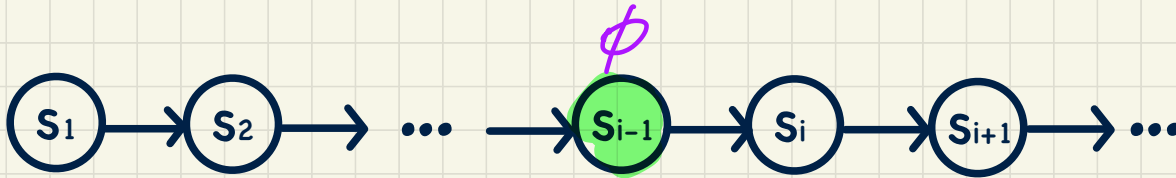
$$\pi \models \boxed{G}\phi \Leftrightarrow \forall i. \boxed{i \gg 1} \Rightarrow \pi^i \models \phi$$

□

$i \in \mathbb{N} \times$
 $\because i=0 \rightarrow \pi^0$ undefined.

Path Satisfaction: Temporal Operations (3)

A **path** satisfies $\text{Future } F\phi \rightarrow \text{Eventually, } \phi \text{ is true.}$
 if some future state satisfies it.

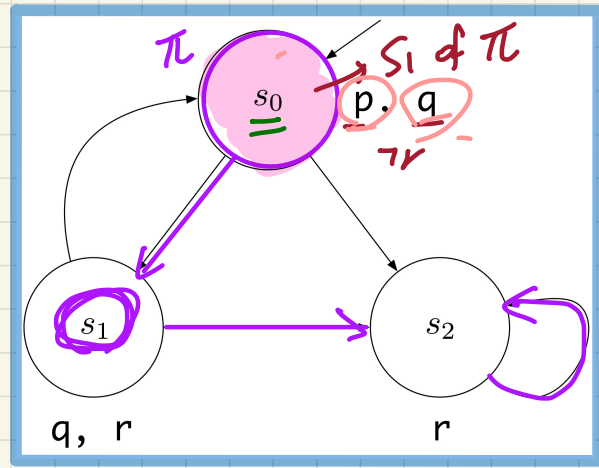


Formulation (over a path)

$$\pi \models \boxed{F} \phi \Leftrightarrow \exists i \cdot i \geq 1 \wedge \pi^i \models \phi$$



Model vs. Path Satisfaction: Exercises (1.1)



Recall: $\pi \models p \Leftrightarrow p \in L(s_1)$

Say: $\pi = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow s_2 \rightarrow \dots$

$$\pi \models \top \quad (\top)$$

$$\pi \not\models \perp \quad (\top) \quad \pi \not\models \perp \equiv \neg(\pi \models \perp)$$

$$\pi \models p \wedge q \equiv \pi \models p \wedge \pi \models q = (\top)$$

$$\pi \models p \vee q \quad (\top) \quad p \in L(s_0) \quad q \in L(s_1)$$

$$\pi \models p \Rightarrow q \equiv \pi \models p \Rightarrow \pi \models q = (\top)$$

$$\pi \models r \equiv r \in L(s_0) \quad (\text{F})$$

$$\pi \models r \Rightarrow p \wedge q \wedge r \equiv$$

$$\pi \models r \quad (\text{F}) \quad \pi \models p \wedge q \wedge r \quad (\top)$$

$$\begin{aligned} \pi^2 \models \top \\ \pi^2 \models \perp \\ \vdots \\ \pi^2 \models r \Rightarrow p \wedge q \wedge r \end{aligned}$$

Exercise: What if we change the LHS to π^2 ?